

The Smart Strap-On Temperature Sensors from Titan Products are designed to monitor pipe flow temperatures and expose the measurements directly onto a BACnet MS/TP or Modbus RTU network.

Providing additional, in-built and networkable I/O, the sensors are supplied with 1 x Digital Output (DO) and 1 x Digital Input (DI), allowing flexible on/off environmental and non-environmental control loops to be set up and read / written to via the BACnet communications. See Control Section for more information.

Measuring multiple environmental conditions over one network bus and integrating this with onboard local control, can drastically reduce on site wiring, installation and commissioning costs.

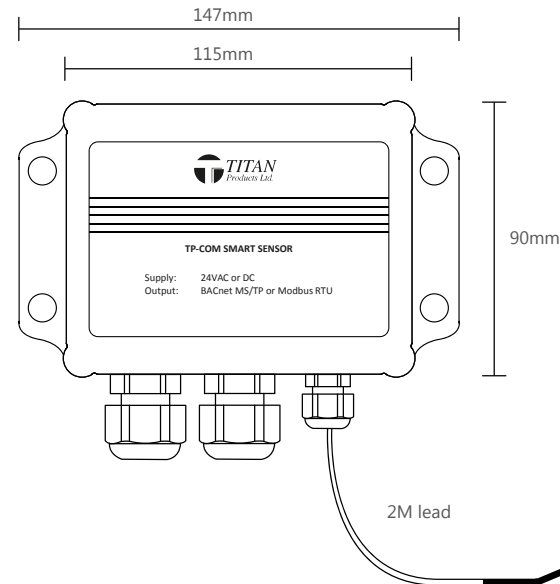
Accurate monitoring and control reduces energy costs and allows the building to be maintained at comfortable occupancy levels which is proven to increase occupant productivity.

Easily addressed via the on-board DIP switches, the sensors are ideal for a wide range of applications that require accurate, networkable monitoring across open systems along with control on demand in building types such as schools, universities, retail, offices and leisure centres.

## Specification

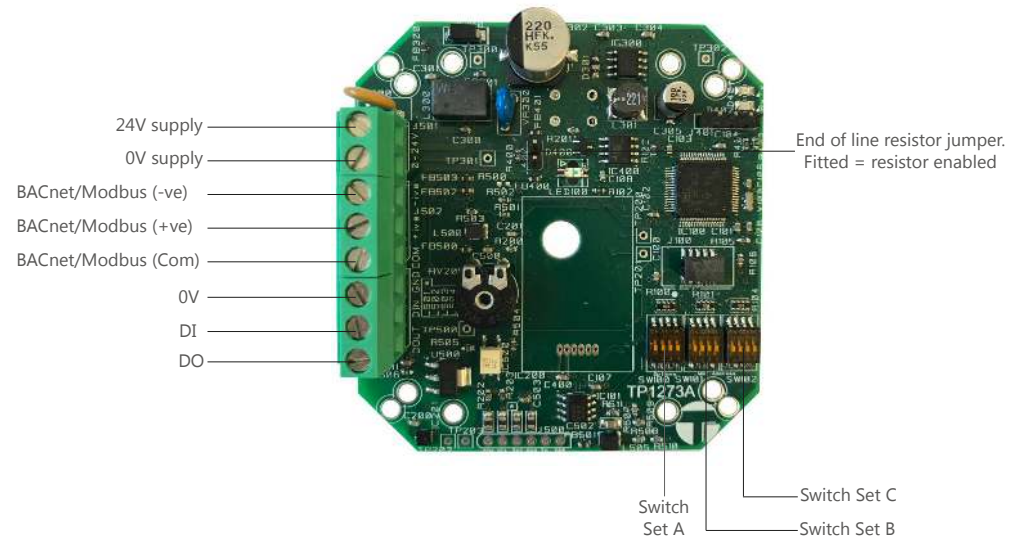
|                        |   |
|------------------------|---|
| Power Supply:          | 24VAC/DC +/- 10%                                |
| Power Consumption:     | 50mA  |
| Communications:        | BACnet MS/TP or Modbus RTC (selectable)         |
| Measured Range:        | Temperature: -10 - 100°C                        |
| Outputs:               | 1 x Digital Output (DO) rated at 350mA          |
| Inputs:                | 1 x Digital Input (DI)                          |
| Baud Rates:            | 9k6, 19k2, 38k4, 57k6 (Modbus)<br>76k8 (BACnet) |
| Accuracy:              | +/- 0.5°C                                       |
| Operating Environment: | -10 to +50°C<br>0-80% non-condensing            |
| Approvals:             | CE / Rohs / WEEE                                |
| Warranty Period:       | 24 Months                                       |
| Location:              | Wall mounted, 1.5m from floor level             |
| Protection:            | IP65 UL94-VO flame retardant                    |
| Terminals:             | 1.0mm recommended, 2.5mm max.                   |
| Country of Origin:     | UK  |
| Product Code:          | TPCS-RT-COM                                     |

## Dimensions



BACnet MS/TP  
or Modbus RTU  
communication

## Connections



## BACnet / Modbus Settings (1-4 Switch A)

| Function                                   | Switch    | Operation  |
|--|-----------|--|
| Communications Selection                   | SW1       | Off = BACnet MS/TP<br>On = Modbus RTC  |
| Modbus Setting (only applicable if SW1 ON) | SW2       | Off = Communications parameters from Modbus Register<br>On = No parity 2 Stop Bits |
| Communications Baud Rate                   | SW3 & SW4 | See table  |

| Baud Rate      | SW3 Setting Position | SW4 Setting Position |
|----------------|----------------------|----------------------|
| 9600           | OFF                  | OFF                  |
| 19200          | ON                   | OFF                  |
| 38400          | OFF                  | ON                   |
| 76800 (BACnet) | ON                   | ON                   |
| 57600 (Modbus) | ON                   | ON                   |

### Note

Switches use Binary to set device BACnet MAC address or Modbus Slave Address.

Value achieved by adding relevant switch values together. See examples in table.

Switches all OFF or all ON are not valid settings for addressing.

Max MAC address for BACnet systems is 127. Max Modbus Slave address is 254.

Address 0 is not valid.

BACnet Device ID = Set MAC address + 151. It is recommended this is altered during commissioning via BACnet communications once the device is discovered by the BMS.

It is recommended to set the network addresses prior to powering up the device.

## BACnet MAC / Modbus Slave Address Settings (1-4 Switches B & C):

|                 | Switch B |         |         |         |  | Switch C |          |          |           |
|-----------------|----------|---------|---------|---------|--|----------|----------|----------|-----------|
| Address example | SW1 (1)  | SW2 (2) | SW3 (4) | SW4 (8) |  | SW1 (16) | SW2 (32) | SW3 (64) | SW4 (128) |
| 1               | ON       | OFF     | OFF     | OFF     |  | OFF      | OFF      | OFF      | OFF       |
| 2               | OFF      | ON      | OFF     | OFF     |  | OFF      | OFF      | OFF      | OFF       |
| 3               | ON       | ON      | OFF     | OFF     |  | OFF      | OFF      | OFF      | OFF       |
| 4               | OFF      | OFF     | ON      | OFF     |  | OFF      | OFF      | OFF      | OFF       |
| 5               | ON       | OFF     | ON      | OFF     |  | OFF      | OFF      | OFF      | OFF       |
| 10              | OFF      | ON      | OFF     | ON      |  | OFF      | OFF      | OFF      | OFF       |
| 15              | ON       | ON      | ON      | ON      |  | OFF      | OFF      | OFF      | OFF       |
| 20              | OFF      | OFF     | ON      | OFF     |  | ON       | OFF      | OFF      | OFF       |
| 50              | OFF      | ON      | OFF     | OFF     |  | ON       | ON       | OFF      | OFF       |
| 100             | OFF      | OFF     | ON      | OFF     |  | OFF      | ON       | ON       | OFF       |
| 150             | OFF      | ON      | ON      | OFF     |  | ON       | OFF      | OFF      | ON        |
| 127             | ON       | ON      | ON      | ON      |  | ON       | ON       | ON       | OFF       |
| 254             | OFF      | ON      | ON      | ON      |  | ON       | ON       | ON       | ON        |

## Control Options

### Smart Sensor Digital Output Activation

The Smart Sensors from Titan Products are all supplied with ON/OFF control options via a Digital Output (DO) as standard.

The DO control can be enabled / disabled via number of methods to suit a number of varying application types. These methods are set up via the BACnet communications of the Smart Sensor and include:

- Manually activated via a write from a connected BMS or Network Controller.
- By allocating the Digital Input (DI) to the DO action. This will enable the DO whenever the DI is active.
- By utilising the in-built Temperature and Humidity Environmental Control features of the sensor. See *Environmental Control Options* below.

It is also possible to manipulate the timing of the DO switching ON or OFF. See *Delay OFF* and *Timer Control* sections below.

### Environmental Control Options

When utilising the in-built Environmental Control functions of the smart sensor, it is possible to set the control logic to activate on a rising or falling environmental condition. See *Rising Control* and *Falling Control* options below.

To allocate a control function to an environmental condition (Temperature) this is selected via MSV301. Once an environmental variable has been allocated to control via MSV301, a control set point, hysteresis settings and the type of control (rising or falling) need to be set.

*Note: Please see full BACnet manual for all BACnet points and more details. The visibility of the control block related objects depends on MSV301 selection. If MSV301 is changed, the device object has to be re-scanned to access the unveiled control objects.*

### Hysteresis settings

The hysteresis acts as the switching differential between the ON and OFF points of control. It is possible to set the hysteresis with the set point balanced in the middle (default), bias the set point below the hysteresis (-) or bias the set point above the hysteresis (+).

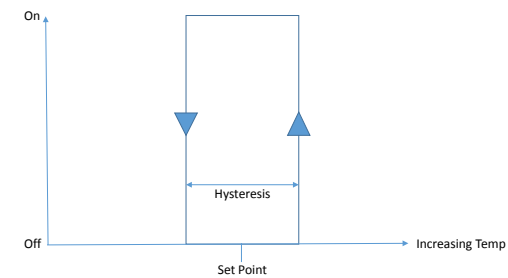
### Rising Control

When selected, Rising Control will enable the sensor DO based on an increase in the measured variable.  
*Application Example:* a cooling cycle being enabled if the temperature increases within a space

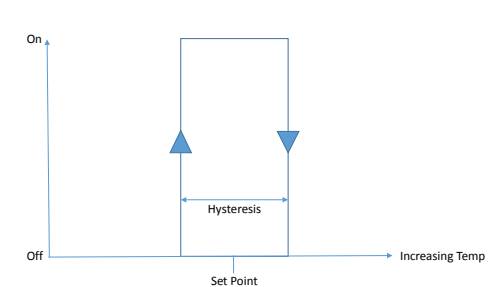
### Falling Control

Falling control will enable the DO based on a decrease in the measured variable.  
*Application Example:* a heating cycle being enabled if the temperature decreases within a space

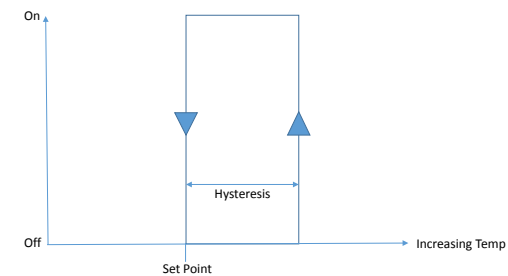
*Rising Control with balanced set point (Default)*



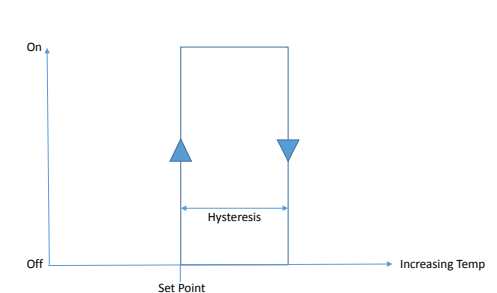
*Falling Control with balanced set point (Default)*



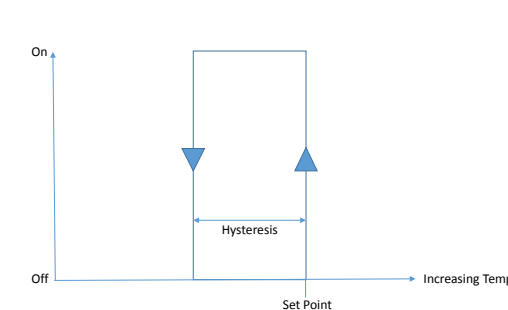
*Rising Control with negatively (-) biased set point*



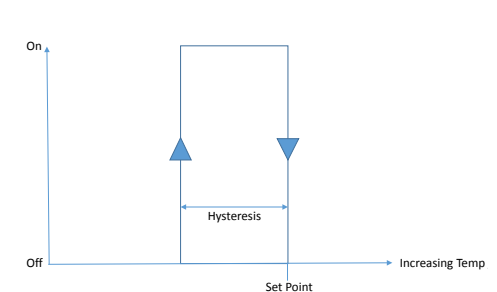
*Falling Control with negatively (-) biased set point*



*Rising Control with positively (+) biased set point*



*Falling Control with positively (+) biased set point*



## Activation of Control

Once the control logic has been set up within the Smart Sensor, it is possible to set when the control loop will be operational. This can be set to run:

- All the time.
- When the on-board Digital Input is activated.
- When activated via the BMS.

This ensures the control is only operational when required.

If set to run all the time, the sensor will activate the DO each time the measured condition reaches the control ON point.

If activated via the Digital Input or BMS the Environmental Control will only be operational until Digital Input or BMS is activated again. At this point the Environmental Control will be inhibited and the sensor will act purely as a monitoring device until the control is activated again.

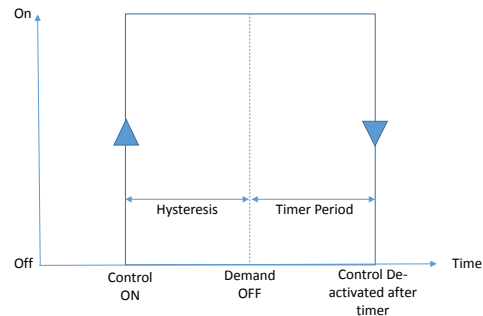
When Environmental Control is being activated by an input on the sensor, the last command from the BMS or Digital Input takes priority.

The BMS can write a direct master override to the DO by writing to BO100.

## Delay OFF

It is possible to apply a Delay OFF timer to the Environmental Control.

This will ensure the Environmental Control action remains activated for a set time after the control is disabled via the digital input or BMS. The Delay OFF is enabled / disabled via the BACnet settings along with the associated timer period.



## Visibility of Control Action

The control action (BV 360) is fully readable via the BACnet communications. This allows the control action within the sensor to be read by the BMS and used to trigger other plant in the space or building via the BMS without utilising the DO on the sensor if required. This feature allows the sensor DO to be triggered by a different method (manually via the BMS or via the DI), creating the possibility for 2 simple control loops via the sensor and BMS.

## Non-Environmental Enable / Disable Control

When no Environmental Control loop is required the DO can be enabled directly via:

- Writing to a Binary Value via BMS
- Enabling the Digital Input.

## Timer Control

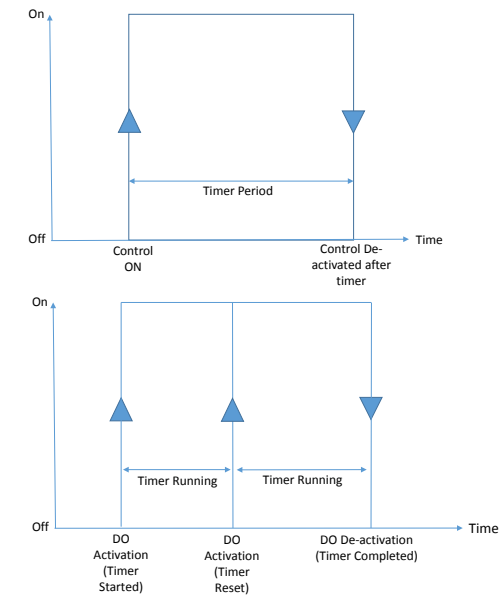
During a non-environmental control action, timer options can be configured as below:

### Timed ON/OFF

On activation via the BMS or Digital Input, the DO is enabled and the set timer period is started. The DO remains enabled until the timer completes or the BMS or DI is activated again to cancel the timer and control. The DO then remains disabled until the next activation. *Application Example: This control action can be used to purge a space with fresh air after a period of high occupancy. E.g. Natural Ventilation applications in educational buildings.*

### Timer Reset Off

On activation via the BMS or DI, the sensor DO is enabled and the set timer is started. The DO will remain enabled until the set timer has run. If either the BMS or DI are activated again before the timer has elapsed, the DO remains enabled and timer will be reset. *Application Example: This control action can be used for occupancy control of lighting or plant equipment within meeting rooms or office spaces.*



## Sensor Notes

1. If the Digital Input is used with a latching switch, Close / Open circuit = ON/OFF. When closed the switch will enable the control or the DO (dependant on configuration) for the duration of the closed circuit. When the Digital Input is open circuit, control or DO (dependant on the configuration) is disabled.
2. If the Digital Input is not used within the application, this objects should be taken out of service to allow the BMS to write to the respective objects to enable / disable the control or DO (dependant on configuration). This feature can be utilised during environmental or non-environmental control strategies.